

CATALOGUE

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1. Introduction

An imbalanced wheel will make the wheel jump and steering wheel wobble while driving. It can baffle the driver to drive, aggrandize the cleft of combine area of steering system, damage the vibration damper and steering parts, and increase the probability of the traffic accidents. A balanced wheel will avoid all these problems.

This equipment adopts the new LSI (Large Scale Integrated circuit) to constitute the hardware system that acquires processes and calculates information at a high speed.

Read the manual carefully before operating the equipment to ensure normal and safe operation. Dismantling or replacing the parts of equipment should be avoided. When it needs repairing, please contact with technique service department. Before balancing, ensure the wheel fixed on the flange tightly. Operator should wear close-fittingsmock to prevent from hanging up. Non-operator does not start the equipment.

No use while beyond the stated function range of manual.

2. Specification and Features

2.1 Specification

Max wheel weight: 65kg
Motor power: 200W
Power supply: 220V/50Hz
Balancing precision: $\pm 1g$
Rotating speed: 200r/min
Cycle time: 8s
Rim diameter: 10"~24"(256mm ~ 610mm)
Rim width: 1.5"~20"(40mm~510mm)
Noise: <70dB
Net weight:82kg
Dimensions: 960mm×760mm×1180mm

2.2 Features

Adopt 9 LED display, it has flexible indicator operating function.

Various balancing modes can carry out counterweights to stick, clamp, or hidden stick etc.

Input data of rim automatically by measure scale.

Intelligent self-calibrating and measure scale self-labeling function.

Self fault diagnosis and protection function.

Applicable for various rims of steel structure and duralumin structure.

2.3 Working Environment

Temperature: 5~50℃

Height above sea level: $\leq 4000m$

Humidity: $\leq 85\%$

3. The Constitution of Dynamic Balancer

Two major components of the dynamic balancer are: machine and electricity:

3.1 Machine

The part of machine consists of support, swing support and main axis; they are together fixed on the frame.

3.2 Electricity system

1. The microcomputer system is made up of the LSI such as new high speed MCU CPU system and keyboard.
2. Automatic measure scale.
3. Testing speed and positioning system consists of gear and opto-electronic

coupler.

4. Two-phase asynchronous motor supplies and controlling circuit.
5. Horizontal and vertical pressure sensor.
6. Hood protection.

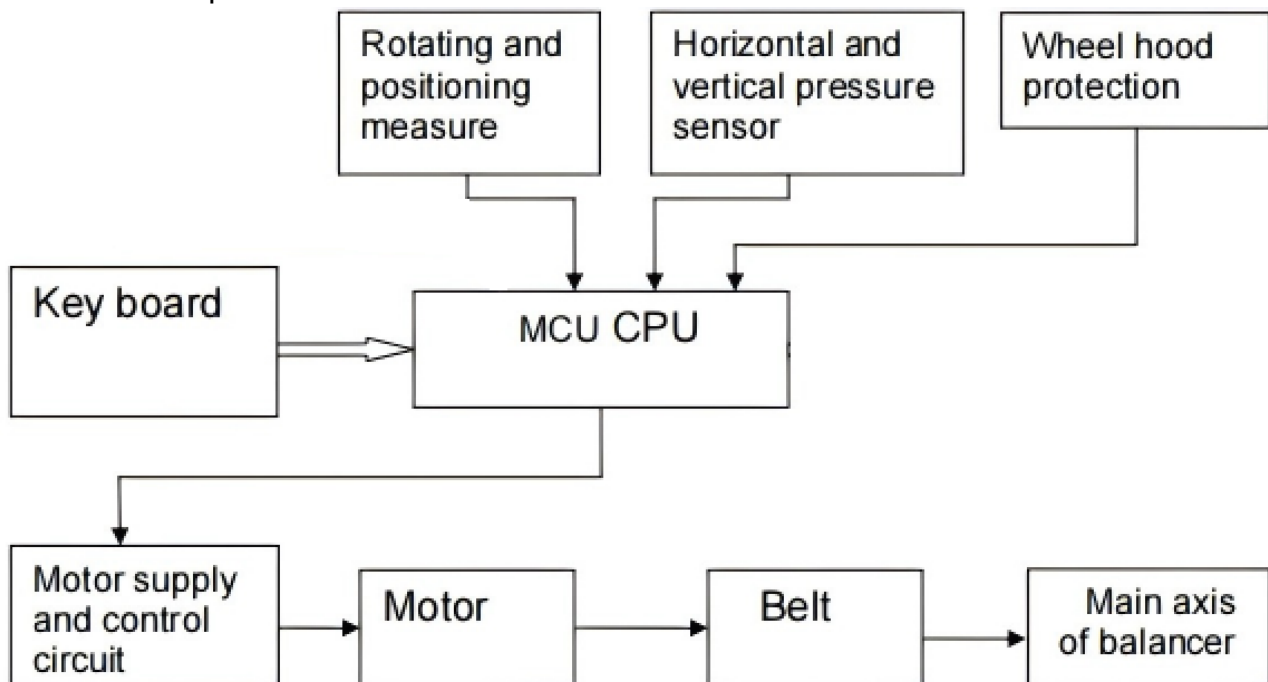


Figure 3-1

4. Installation of Dynamic Balancer

4.1 Opening and Checking

Open the package and check whether there are damaged parts. If there are some problems, please do not use the equipment and contact with the supplier. Standard accessories with equipment are shown as follow:

Screw stud of drive axis	1
Balancing pliers	1
Allen wrench	1
Measure caliper	1
Locking nut	1
Adapter (cone)	4
Counterweight (100g)	1
Protection hood	1

4.2 Installing machine

4.2.1 The balancer must be installed on the solid cement or similar ground, unsolidified ground can bring measuring errors.

4.2.2 There should be 50cm around the balancer in order to operate conveniently.

4.2.3 Nail anchor bolts on the base's mounting hole of balancer to fix the balancer.

4.3 Installing hood

Install the frame of hood on the equipment: plug the pipe of protection hood into the hood shift (behind the cabinet), then fix with M10×45 screws.

4.4 Installing screw stud of drive axis

Install screw stud of drive axis on the main axis , then screw down the bolt. (Refer to figure 4-1)

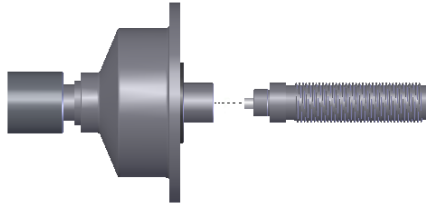


Figure 4-1

(**Notice:** a wheel can be installed on the main axis before screwing down, then hold the wheel by hands in order to prevent the main axis revolving together with the bolt.)

5. LED display control panel and function keys

Figure 5-1 displaying on the LED panel

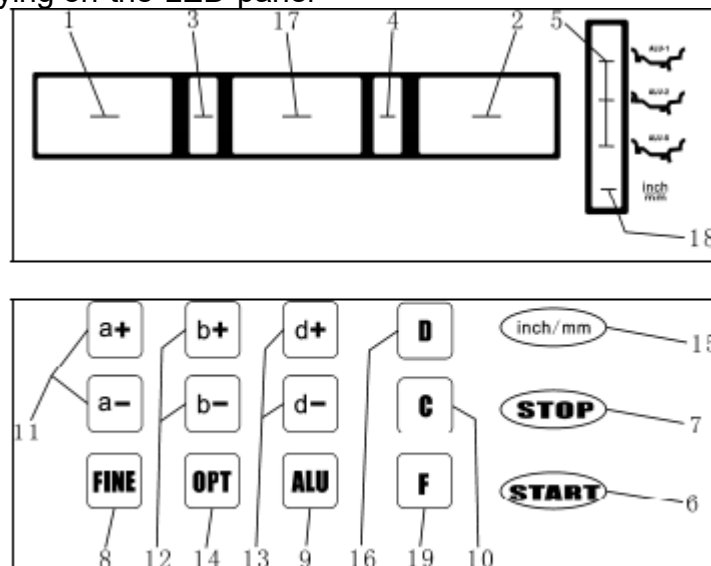


Figure 5-1

Part name of panel and signification

- 1-Digital readout, amount of imbalance, inside or "DISTANCE" dimension
- 2-Digital readout, amount of imbalance, outside or "DIAMETER" dimension
- 3-Digital readout, position of imbalance, inside
- 4-Digital readout, position of imbalance, outside
- 5-Indicator, "ALU" correction mode selected
- 6-Push button, cycle start
- 7-Push button, emergency and selection of special functions
- 8-Push button, unbalanced display pitch and threshold
- 9-Push button, selection of "ALU" mode of correction
- 10- Push buttons for recalculation and self-calibration
- 11- Push buttons, manual DISTANCE (a) setting
- 12- Push buttons, manual WIDTH (b) setting
- 13- Push buttons, manual DIAMETER (d) setting
- 14- Push button, optimization of unbalance and split unbalance
- 15- Selection of dimensions, inch/mm
- 16- Push button, self-diagnostics, self-calibration and split unbalance
- 17- Digital readout, "STATIC" unbalance or "WIDTH" dimension
- 18- Indicator of dimensions in mm
- 19- Selection, "STATIC" or "DYNAMIC" correction

N.B. Only use the fingers to press push buttons. Never use the counterweight pincers or other pointed objects.

6. Installation and Demounting of the Wheel

6.1 Checking the wheel

The wheel must be clean, none sand or dust on it, and remove all the primal counterweights of the wheel. Check the tyre pressure whether up to the rated value. Check positioning plane of rim and mounting holes whether deformed.

6.2 Installing the wheel

6.2.1 Select the optimal cone for the center hole when there is center hole on the rim.

6.2.2 Two ways of installing the wheel: A. positive positioning; B. negative positioning.

6.2.2.1 Positive positioning (refer to figure 6-1):

Positive positioning is commonly used. It operates easily, and it is applicable for various rims of common steel structure and thin duralumin structure.

6.2.2.2 Negative positioning (refer to figure 6-2):

Negative positioning is used to ensure the inner hole of steel rim and main axis is positioning accurately when the outside of wheel deforming. Apply for all the steel rims, thick steel rims especially.

6.2.3 Install wheel and cone on main axis. Ensure the cone can clamp the wheel before screwing handle. Wheel can rotate after screwing down.

6.3 Demounting the Wheel

6.3.1 Demount the handle and cone.

6.3.2 Put the wheel up, and then take it down from main axis.



Figure 6-1



Figure 6-2

Note: do not slip wheel on main axis to prevent main axis from scuffing while installation and demounting the Wheel

7. The input methods of date of rim

7.1 The power-on state of the machine

After the power-on of the machine, it starts initialization automatically. The initialization will be finished after two seconds. The machine enter natural dynamic (clamp counterweights on the correction plane of the both edged sides of rim) mode automatically, as in Figure 7-1, ready for input date of rim.

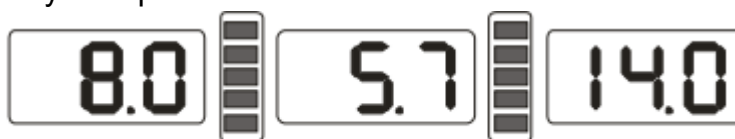


Figure 7-1

7.2 Date of wheel input method for normally dynamic balance mode

7.2.1 After the power-on of the machine, it enter the normal balance mode

7.2.2 Input date of rim:

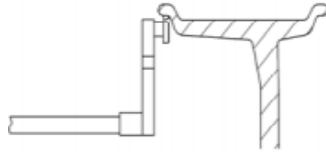


Figure 7-2

Rotate the measure scale, pull the scale head to inside concave on the edge of the rim, etc figure 7-2, first LED all off, then display ect figure 7-3, waiting put back scale.

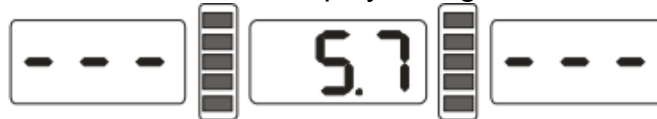


Figure 7-3

When scale back to zero position, LED display value is date of rim.

7.2.3 When measure values with fact value of rim differ, you need self-calibration of scales then measure again or manual input date of rim.

7.2.4 Input date of rim width

Use manual plastic width measure scale, measure the width value of rim then press b+ or b- key input date by manual.

7.3 The date input method of ALU-S mode:

Normally from normal mode change to other mode, do not need input rim date again, just press ALU key change to you select mode in directly is fine, only ALU-S mode have special input method, ALU-S mean is special mode, include below two kind modes (Figure 7-6):



Figure 7-6

ect figure 7-7 or 7-8, Rotate the measure scale, pull the scale head to inside of the rim(FI)(this position is your select to stick balance weight on the inside), measure distance(a) and diameter (dI) of inside of the rim, ect figure 7-9, then continue rotate measure scale, pull the scale head to outside of rim(FE) (this position is your select to stick balance weight on the outside), measure distance(aE) and diameter (dE) of outside of the rim, ect figure 7-10, enter ALU-S mode.

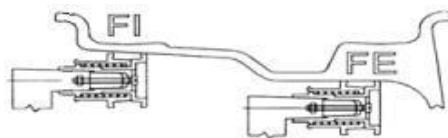


Figure 7-7

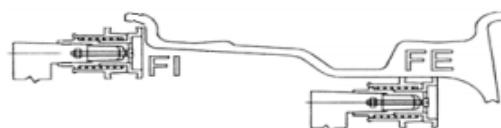


Figure 7-8

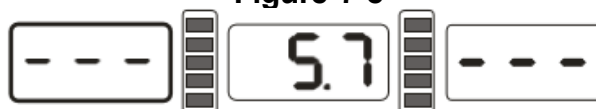


Figure 7-9



Figure 7-10

When scale back to zero position, LED will be display aE and dI value. Press a+, a- can be adjust a value; press b+, b- can be adjust aE value; press d+,d- can be adjust dI value; press FINE key LED will display dE value, hold press FINE key and press d+, d- adjust dE value.

8. Calibration of measure scale

The measure scale was labeled before ex-factory, but the labeled value may vary because of transportation. Therefore, users can label it themselves before using the balancer.

After the power-on, the initialization is finished. Thus, users can label the measure scale

8.1 Calibration of rim distance scale

8.1.1 Press and hold STOP key and press FINE key, ect 8-1, press STOP key or C key to exit.



Figure 8-1

8.1.2 Move scale to 0(zero) position, press ALU key, ect 8-2, press STOP key or C key to exit.



Figure 8-2

8.1.3 Move scale to 15, press ALU key, ect 8-3, end of self-calibration, put back measure scale.



Figure 8-3

8.2 Calibration of diameter scale

8.2.1 Installation middle size tyre on principal axis, press and hold STOP key, and press OPT key, ect 8-4, press STOP key to exit;



Figure 8-4

8.2.2 Press d+ or d- adjust value to current rim diameter value, press ALU key, ect 8-5;

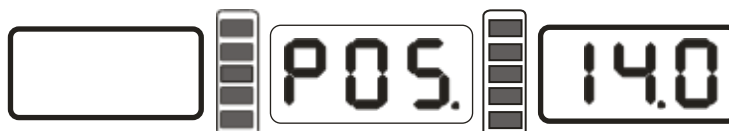


Figure 8-5

8.2.3 Move scale, put scale head on the inside edge of rim ect 7-2, press ALU key, ect 8-3, self-calibration end, put back scale.

9. The Self-calibrating of Dynamic Balancer

The self-calibrating of dynamic balancer was finished before ex-factory, but the system parameter may vary because of long-distance transportation or long-term use, which may cause error. Therefore, users can make self-calibrating after a period of time.

9.1 After the power-on of the machine, the initialization is finished ect 7-1, install a can clip counterweight and comparatively balanced middle size tyre, follow step 7 input date of rim;

9.2 Press D key and C key, ect figure 9-1, (lay down protect hood), press START key, going to nextstep, press STOP key or C key to exit;



Figure 9-1

9.3 After axis stop, ect figure 9-2,(open protect hood)clip a 100 gram counterweight on anywhere of outside of rim, (lay down protect hood)press START key, going to nextstep, press STOP key or C key to exit;



Figure 9-2

9.4 After axis stop, ect 9-3, calibration end. Demount tyre, now balancer ready to work.



Figure 9-3

NB: when you doing self-calibration, input date of rim must be correct,100 gram counterweight must be correct, otherwise self-calibration result will be wrong, wrong self-calibration will be make balancer measure precision decline.

10. The Balancing Operation of Wheel

10.1 Balance mode change operation

10.1.1 Dynamic and static balance mode switch: press F key.

Dynamic balance mode: clip counterweight on inside and outside edge of rim (balancer tolerant normal balance mode),ect figure 10-1.

ST mode: static balance measure mode, stick counterweight on middle of rim, ect figure 10-2.

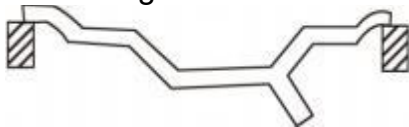


Figure 10-1



Figure 10-2

10.1.2 ALU balance mode switch key (ALU key), switch CPU system between

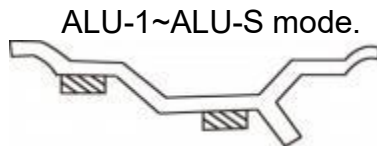


Figure 10-3

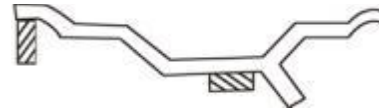


Figure 10-4

ALU-1 mode: stick counterweight on inside and outside of spoke of rim, ect 10-3.

ALU-2 mode: clip counterweight on inside edge of rim, stick counterweight on outside (inside of spoke),etc figure 10-4.

ALU-S mode: This is a special balance mode (include ALU-1 and ALU-2), for Counterweight split and Hidden-Stick Mode.

Counterweight split and Hidden-Stick Mode:

ALU-S mode, if the outside (inside of spoke) counterweight position between of two spokes, ALU-S mode can split the counterweight for two. The divided counterweight, just place on the back of two spokes near the former counterweight, in order to hide the counterweight. ect figure 10-5.



Figure 10-5

10.2 Normal balance mode operation process

10.2.1 Follow figure 7.2 input date of rim.

10.2.2 lay down protect hood and press START key, wheel spinning, after stop two side LED display wheel both side imbalance weight, when middle LED display OPT, can choice imbalance optimize;

10.2.3 Slowly spin wheel, when inside counterweight position indicator light (figure 5-1(3)) all on, clip correspond counterweight on 12 o'clock position on inside of rim, ect figure 10-6;

10.2.4 Slowly spin wheel, when outside counterweight position indicator light (figure 5-1(4)) all on, clip correspond counterweight on 12 o'clock position on outside of rim, ect figure 10-7;

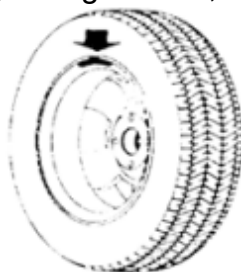


Figure 10-6

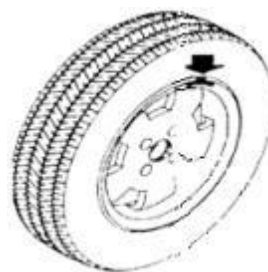


Figure 10-7

10.3 Static balance (ST) operation process

10.3.1 Move measure scale to middle of rim, and measure the data of rim;

10.3.2 Press F key, switch to static balance (ST) mode.

10.3.3 lay down protect hood and press START key, wheel spinning, after stop

middle LED display wheel static imbalance weight, when middle LED display OPT, can choice imbalance optimize;

- 10.3.4 Slowly spin wheel, when both side counterweight position indicator light (figure 5-1(3), (4)) all on, stick counterweight on 12 o'clock position middle of rim. ect figure 10-8.



Figure 10-8

10.4 The operation process of M1 to M2 mode

- 10.4.1 Follow 7.2 input date of rim;
- 10.4.2 Press ALU key, switch to correspond balance mode.
- 10.4.3 lay down protect hood and press START key, wheel spinning, after stop two side LED display wheel both side imbalance weight, when middle LED display OPT, can choice imbalance optimize;
- 10.4.4 Slowly spinwheel, when inside counterweight position indicator light (figure 5-1(3)) all on, follow different mode clip or stick counterweight on 12 o'clock position inside of rim.
- 10.4.5 Slowly spinwheel, when outside counterweight position indicator light (figure 5-1(4)) all on, follow different mode clip or stick counterweight on 12 o'clock position outside of rim.

10.5 ALU-S balance mode operation process

★ Process of manual stickup counterweight

- 10.5.1 Follow figure 7.3 input date of rim.
- 10.5.2 lay down protect hood and press START key, wheel spinning, after stop two side LED display wheel both side imbalance weight, when middle LED display OPT, can choice imbalance optimize;
- 10.5.3 Slowly spin wheel, when inside counterweight position indicator light(figure 5-1(3)) all on, if is follow figure 7-8 input date of rim, nextstep follow 10.2.3 clip counterweight, if Notec figure 10-9 of left sideshow, stick counterweight on 12 o'clock position on inside of rim.
- 10.5.4 Slowly spin wheel, when inside counterweight position indicator light(fight 5-1(4)) all on, stick correspond counterweight on 12 o'clock position on outside of rim, ect figure 10-9 right side;

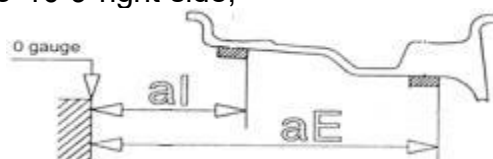


Figure 10-9

★ Process of automatic stickup partition Counterweight

- 10.5.5 Follow figure 7.3 input date of rim
- 10.5.6 lay down protect hood and press START key, wheel spinning, after stop two side LED display wheel both side imbalance weight, when middle LED display OPT, can choice imbalance optimize;
- 10.5.7 If is follow figure 7-8 input date of rim, follow 10.2.3 clip counterweight on inside edge of rim. Press STOP key and ALU key, all middle of LED display - -, follow 10.3.9 stick counterweight on outside of rim.
- 10.5.8 If is follow 7-7 input date of rim, press STOP key and ALU key, all middle of LED display - -,insert correspond counterweight into the scale head slot,

slowly spin wheel, when inside counterweight position indicator light(fight 5-1(9)) all on, draught scale, when inside counterweight position indicator light(fight 5-1(3)) all on, slowly pull out measure scale and middle of LED display as figure 10-10, then turn the scale, stick counterweight on the rim, ect figure 10-12;



Figure 10-10

10.5.9 Insert correspond counterweight into the scale headslot, slowly spinwheel, when outside counterweight position indicator light(fight 5-1(4)) all on, draught scale, when inside counterweight position indicator light(fight 10-11) all on, turn scale, stick counterweight on the rim, ect figure 10-12;



Figure 10-11

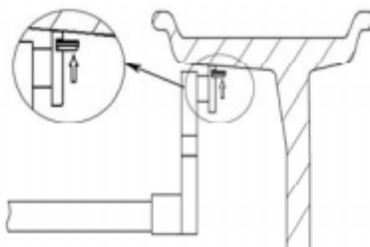


Figure 10-12

NB: when use scale to stick counterweight automatically, make sure LED must display - - -, if not, do not move scale, press STOP and ALU key, then middle LED display - - -, now you can move scale for automatically sticking counterweight.

10.6 The of counterweight hide-stick mode

Counterweight Hidden-Stick mode is only available in ALU-S mode, this mode can split this position into two parts and make these two new positions hide behind the spoke, so you can achieve this hide purpose. This balance mode only available in ALU-S mode.

In 10.3 operation process, if outside counterweight not hide behind the spoke, but you still want it hide behind the spoke, you can follow below operation:

10.6.1 Press a+ key, back to figure 7-1 interface, press D key and OPT key, display input numbers of spoke(figure 10-13),press b+ or b- key input spoke numbers, press D key and OPT key to save and return, slowly turn the wheel, turn the near by imbalance position of spoke on the top(12 o'clock),press D and OPT key to enter hide stick mode, and then press D and OPT key to exit;

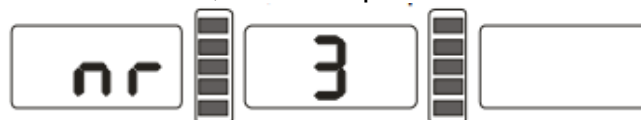


Figure 10-13

★ Split manual stick operation

10.6.2 Stick inside operation same 10.3.3;

10.6.3 Slowly spinwheel, when outside counterweight position indicator light(figure 5-1(4)) all on, stick counterweight on 12 o'clock position outside of rim, ect figure 10-18 right side;

10.6.4 Slowly spin wheel again, when outside counterweight position indicator light(figure 5-1(4)) all on, find second position, stick counterweight on 12 o'clock position outside of rim, ect figure 10-9 right side;

★ Split automatic stick operation

10.6.5 When stick inside, operation same 10.3.7 and 10.3.8

10.6.6 Slowly spinwheel, when outside counterweight position indicator light(figure 5-1(4)) all on, find first position, draught scale, when outside counterweight position indicator light(figure 10-11) all on, turn scale, stick counterweight on rim(ect figure 10-12);

10.6.7 Slowly spinwheel, when outside counterweight position indicator light(figure 5-1(4)) all on, find second position, draught scale, when outside counterweight position indicator light(figure 10-11) all on, turn scale, stick counterweight on rim(ect figure 10-12).

NB: when use scale to stick counterweight automatically, make sure LED must display - - -, if not, do not move scale, press STOP and ALU key, then middle LED display - - -, now you can move scale for automatically sticking counterweight.

10.7 Recalculation

Before wheel balance testing, sometimes may forget input current date of rim, you can after wheel balance testing input date of rim reintroduce, at this time do not need press START key, just press recalculation key (C) system will follow new date of rim calculation imbalance measure. Even interface currently display imbalance value, press C key, can be check currently input date of rim.

11. Imbalance optimize

If wheel imbalance value over 30 gram, system will be display "OPT", clue on process imbalance optimize.

Imbalance optimize have two operation method:

11.1 Already display balance value

If already finish balance testing, when you need process imbalance optimize, press OPT key, display ect figure 11-1;



Figure 11-1

Use chalk mark a reference point on the flange plane and rim and tyre, use tyre changer exchange rim and tyre 180° ; Reinstall wheel on the balancer and make sure mark of reference point between the flange plane and rim must be on the same potion. press START key, display ect figure 11-2;



Figure 11-2

ect Figure 11-2, left LED display percent of optimize, if before optimize static value is

40 gram, optimized is 85%, so after optimize static value only 6 gram remain ($15\% \times 40\text{gram} = 6\text{gram}$);

Slowly spin wheel by hand, when both side two of position indicator light flashing (figure 11-3), use mark pen make a mark on the tyre;

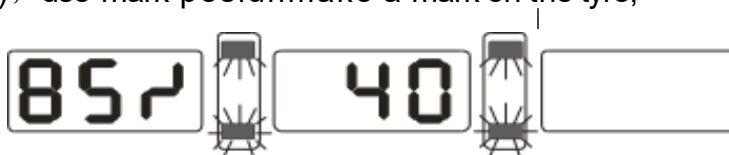


Figure 11-3

Slowly spin wheel by hand again, when both side one of middle position indicator light flashing (figure 11-4), use mark pen make a mark on the rim;

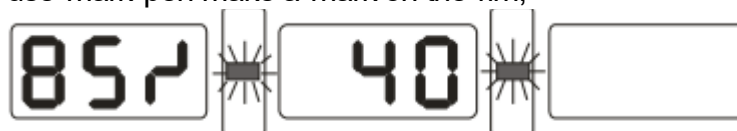


Figure 11-4

Remove the wheel from balancer, use tyre changer remove tyre from rim, make tyre and rim marks together, use tyre changer fit tyre on the rim, optimize complete.

11.2 Before testing of power on, also process imbalance optimize directly

Turn on the power, installation wheel, press OPT key, left side display OPT, press START key, display ect figure 11-1, then follow 11.1 step to operation. Press STOP key to stop operation.

12. Gram-Oz conversion operation

This operation for counterweight maund conversion (gram-Oz).

12.1 Press STOP key and a+ key or a-, display ect figure 12-1, denotation currently maund is gram.

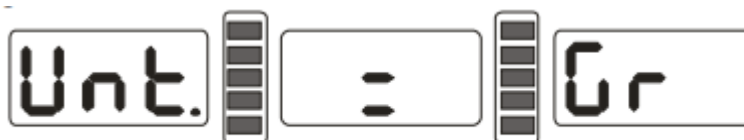


Figure 12-1

12.2 Press b+ or b- key, display ect figure 12-2, denotation currently maund is Oz;



Figure 12-2

12.3 Press b+ or b- key for switch maund between gram and Oz;

12.4 Press a+ key to save setup and exit.

13. INCH and MM conversion operation

This operation for input dimension B value and D value conversion (INCH-MM).

Press INCH/MM key, long measure of LED 6 display value B and LED 7 display value D can be change between INCH/MM. if in the LED display window right underside have a radix point mean currently long measure is INCH, if not, long measure is MM.

14. Protect hood function and protect setting

This function can besetting closing protect hood motor start or lay down protect hood properly, then press START key to start motor.

Press STOP key and C key, ect figure 14-1, right display currently state, when display ON, denotation function on, when display OFF, denotation function off.

Press b+ or b- key for switch protect hood function between “ON” and “OFF”;

Press a+ key to save currently settings and exit.

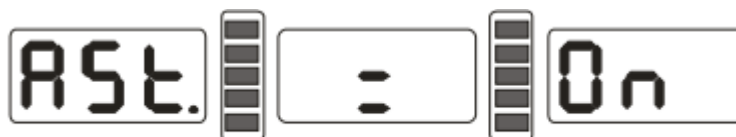


Figure 14-1

15. Other function settings

15.1 Minimum value display settings

After select minimum value display ,even wheel imbalance value less than setting value, result will be display 0(zero),press FINE key, will be display fact imbalance value. Press STOP and D key, ect figure 15-1,denotation imbalance value less than 5 gram, display is 0g(zero gram),press b+ or b- key setting minimum value, are 5 and 10 and 15gram three distinctions. Press a+ key to save settings and enter nextstep;

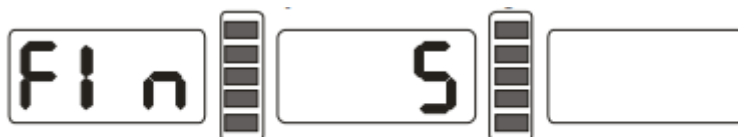


Figure 15-1

15.2 Key-tone clue on function settings

This function can turn on or turnoff key-tone, even turn on this function, every time press key, system will be emit a “di” of tone, even turnoff this function, press key not tone. From 15.1 press a+ enter settings, ect figure 15-2, right side display ON denotation function on, display OFF denotation function off. Press b+ or b- key, function will be switch between “ON” and “OFF” . Press a+ key to save settings and enter nextstep;



Figure 15-2

15.3 Display monitor brightness settings

This function will follow use environment and user need, setting display brightness. From 15.2 press a+ enter settings, ect figure 15-3, right side display brightness grade, altogether is 8 levels, level 1 is darkest, level 8 is brightest, default is level 4.press b+ or b- key, function will be switch brightness levels. Press a+ key to save settings and enter next step;



Figure 15-3

16. Machine self test function

This function will be check all kinds input signal whether right working and provide gist for trouble analyses.

16.1 LED and indicator light check

Press D key, whole LED and indicator light all turn on, this function can be check LED or indicator light whether appear damage, press C key to exit, after about 5 seconds display ect figure 16-1,enter position sensor check. Press C key to exit.



Figure 16-1

16.2 Position sensor signal check

This function can be check position sensor and principal axis and main board circuit whether damage.

Slowly turn principal axis, right side LED display number appear change, clockwise turn, and value increase. Anticlockwise turn, value minish, correct value change is between 0 to 63.press ALU key, enter distance sensor check. Press C key to exit.

16.3 Distance sensor signal check

This function can be check distance sensor and main board signal circuit whether damage.

From 16.2 press ALU key enter, ect figure 16-2, move measure scale, value will be change, value follow move more increase. Press ALU key, enter diameter sensor signal check. Press C key exit.

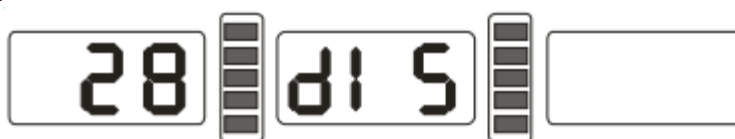


Figure 16-2

16.4 Diameter sensor signal check

This function can be check diameter sensor and main board signal circuit whether damage.

From 16.3 press ALU key enter, ect figure 16-3, turn measure scale, value will be change, anticlockwise turn, value increase, clockwise press turn, value minish. Press ALU key, enter press sensor signal check. Press C key exit.

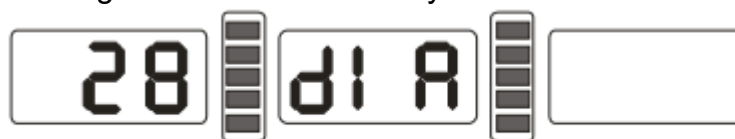


Figure 16-3

16.5 Press sensor signal check

This function can be check press sensor and main board signal circuit and power supply whether damage.

From 16.4 press ALU key enter, ect figure 16-4, gently press principal axis, right and left LED display value will be change, press ALU key to enter press sensor signal check.Press C key exit.



Figure 16-4

17. Safety Protections and Trouble Shooting

17.1 Safety protection

- 17.1.1 Under the circumstance of operation, if the machine does not operate normally, press STOP key, the rotating wheel will stop immediately.
- 17.1.2 If hood is not laid down, press START key, the wheel will not rotate.
- 17.1.3 Under the circumstance of operation, if hood open, the rotating wheel will stop immediately.

17.2 Trouble shooting

- 17.2.1 After press START key, principal-axis not spinning, LED display Err-1.check motor, computer board and cable connections;
- 17.2.2 After press START key, principal axis rotate, LED display Err-1.check position sensor, computer board and cable connections;
- 17.2.3 If balance test already end, balancer still rotates for a long time, does not brake, check brake resistance, power supply board, computer board and cable connections;
- 17.2.4 If turn on the power LED display ect figure 17-1,need measure scale self-calibration or adjust a-value sensor or replacement new sensor;



Figure 17-1

- 17.2.5 Automatic measure rim, advert display date whether difference with trim size of rim, if difference, need measure scale self-calibration;
- 17.2.6 If turn on the power have not display, check power switch indicator light whether working, if not, check power supply first, then check power supply board and computer board and cable connections;
- 17.2.7 Precision not nicety, commonly hurtful not from balancer, may wheel installation wrong or counterweight heft not nicety or 100 gram counterweight for balance self-calibration not nicety, must be always keep manufactory's 100 gram counterweight safety for self-calibration only.
- 17.2.8 Date not astaticism, repeat difference, commonly hurtful not from balancer, may wheel installation wrong or floor not messiness not level off, may as well fixation balancer by bolt. Sometimes not connection earth wire may appear this phenomenon.

Hint: check precision right method:

Input right date of wheel(a. b. d value),consult instruction do a self-calibration, press START process balance operation, note down date of first time, clip 100 gram counterweight on the outside edge of wheel(when outside indicator light all on is top zenith position),press START key again process balance operation, this date of outside display addition date of first time, should amount 100 ± 2 ,manually slowly turn the wheel, when light of outside all on, check 100 gram counterweight whether at 6 o'clock position, if not amount 100 gram or 100 gram counterweight not at 6 o'clock position, indicate balancer precision have problem, if amount is 100 gram, follow same method check inside, check inside whether amount is 100 gram and at 6 o'clock.

18. Maintenance

18.1 The daily maintenance of non- professionals

Before the maintenance, please switch off the power-supply.

18.1.1 Adjust the tension of the belt.

18.1.1.1 Dismantle the hood.

18.1.1.2 Unlash the screw of the motor, move the motor till the belt'stension is proper, and emphatically press the belt downwards about 4mm.

18.1.1.3 Tighten the screw of the motor and cover the hood.

18.1.2 Check whether the wire of electricity part connects reliably.

18.1.3 Check whether the pressed screw of the main axis is loose.

18.1.3.1 Locking nut can not fix wheel tighten on main-axis

18.1.3.2 Use hexagonal wrench to tighten the pressed screw of the main-axis.

18.2 The maintenance of professionals

The maintenance of professionals can only be carried out by the professionals from the factory.

18.2.1 If the imbalance value of tested wheel has obvious errors and does not improve after self-calibrating, this proves the parameter in the machine has altered, so the user should ask for professionals.

18.2.2 The replacing and adjustment of pressure sensor should be operated according to the following methods, and the operation should be carried out by professionals.

The steps are as follows:

1. Unlash the No.1, 2,3,4,5 nuts.

2. Dismantle the sensor and nut.

3. Replace No.6, 7 the sensor organ.

4. Install the sensor and the nut according to the Figure 18-1. (Pay attention to the sensor'sdirection.)

5. Tighten No.1 nut emphatically.

6. Tighten the No.2 nut to make the main axis and the flank of cabinet, and then emphatically tighten the No.3 nut.

7. Tighten the No.4 nut (not too emphatically), then tighten No.5 nut.

18.2.3 The replacing of circuit board and the organ on it should be carried out by professionals.

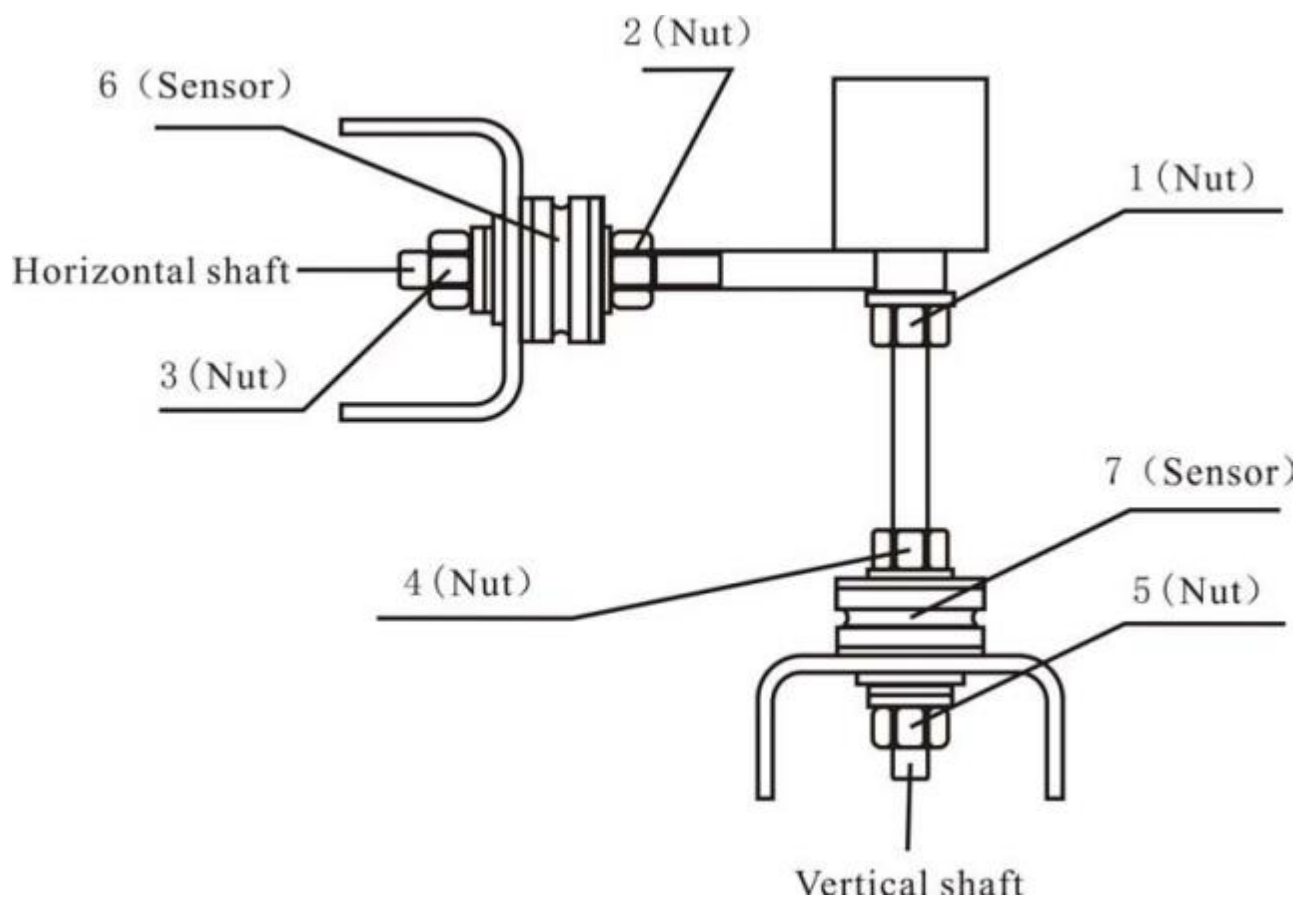


Figure 18-1

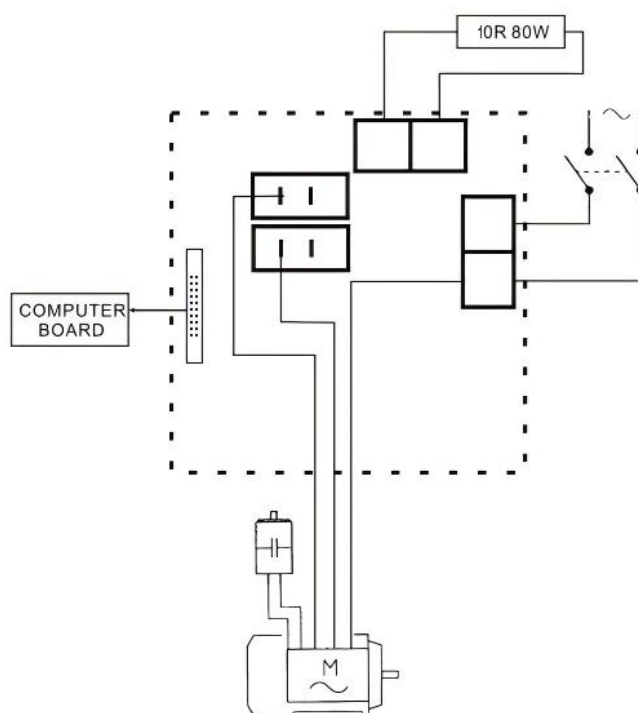
19. Trouble-error code list

When balancer display hint of error, can follow consult below list to remove the trouble:

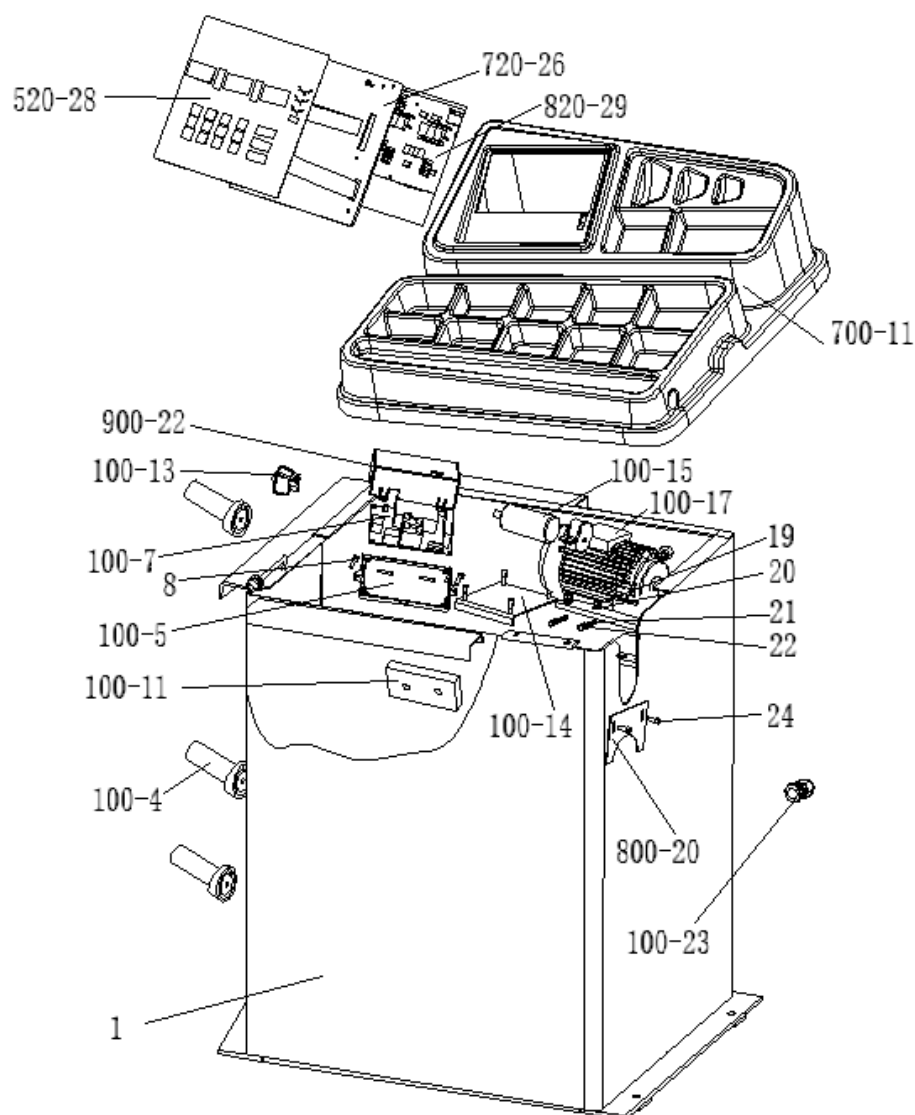
Code	meanings	cause	remedy
Err 1	principal axis not spin or have not spin signal	1.motor fault 2.position sensor fault 3.power supply board fault 4.computer board fault 5.connection-peg untouched	1.change motor 2.change position sensor 3.change power supply board 4.change computer board 5.check cable connections
Err 2	The rotation is lower than 60r/min	1. position sensor fault 2. wheel not impacting or weight too light 3. motor fault 4. driving belt too loose or too tighten 5. computer board fault	1. change position sensor 2.repeat impacting wheel 3. change motor 4.adjust driving belt elasticity 5. change computer board
Err 3	Miscalculation	too high imbalance	Repeat the self-calibration change computer board
Err 4	principal axis Wrong rotation direction	1. position sensor fault 2. computer board fault	1. change position sensor 2. change computer board
Err 5	Protection hood not lay down	1.when press START key, Protection hood not lay down 2. jiggleswitch fault 3. computer board fault	1.follow right method operation 2.change jiggleswitch 3. change computer board
Err 6	Sensor signal transact circuit not working	1. power supply board fault 2. computer board fault	1. change power supply board 2. change computer board
Err 7	Lose date of interior	1. Incorrect self-calibration 2. computer board fault	1. Repeat the self-calibration 2. change computer board
Err 8	Self-calibration memory fault	1. not put 100 gram on the rim when self-calibration 2. power supply board fault 3. computer board fault 4. press sensor fault 5. connection-peg untouched	1.follow right method repeat self-calibration 2. change power supply board 3. change computer board 4.change press sensor 5.check cable connection

20. Power supply layout diagram

20.1 220 V Connection

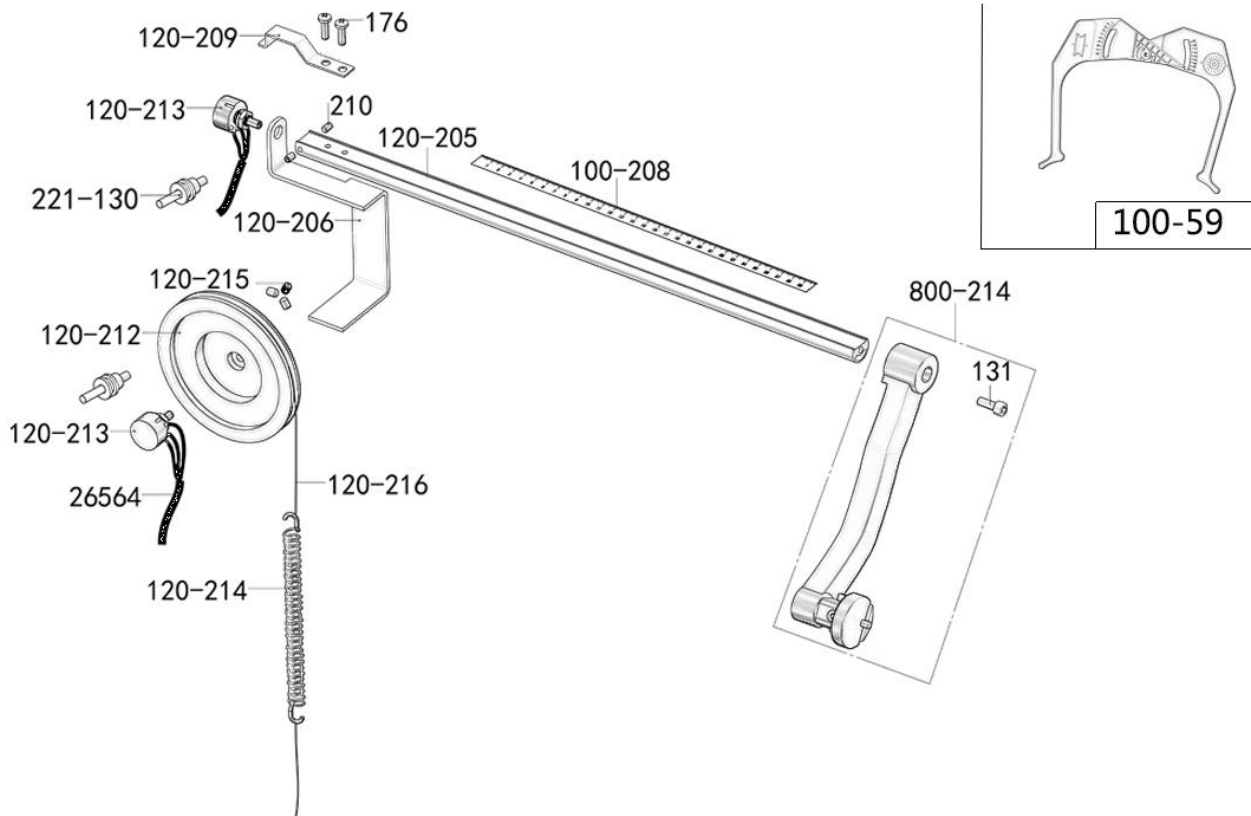


21. Exploded drawings

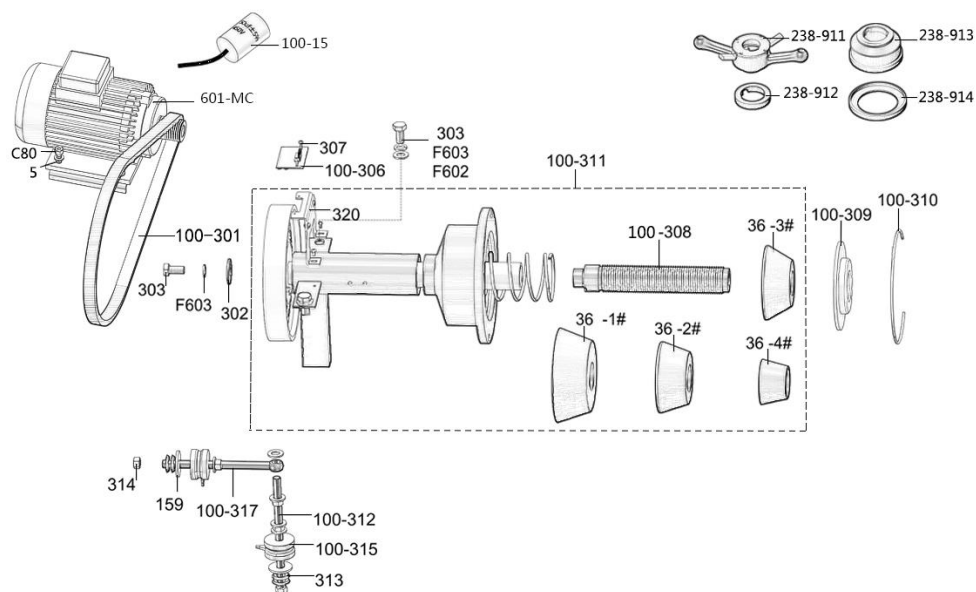


No.	Description	Specification	PLM Code
1	Body	S728	Optional
100-4	Tools hang	U100	JZ12001800019
100-11	Resistor	10Ω-80W\Cement	DD21005000002
100-5	Electric Board Support	U100	JZ12001800037
8	Screw	ST4.8*16	FJ19005000001
100-7	Power board	U828	JZ12300200019
100-13	Power switch	KCD4\middle\green	DD12011000004
900-22	Box	U100	JZ12000200131
700-11	Head with tools-tray	S700	JZ12001800088
520-28	KEY board	U520*U0HU01	JZ12300500089
720-26	Display Fixed Plate	S720*Option-2	JZ20203100014
820-29	Computer board	U820	JZ12300100092
100-14	Motor adjust board	220V	JZ20203100023
100-15	Capacitor	15uF450V	DD20001000004
100-17	Motor	220-240V\50HZ\1PH\0.2KW	DD01001000072
19	Nut	M6\White zinc\Carbon steel	FJ21011000023
20	Washer	6*14*1.2\White zinc	FJ15006000095
21	Nut	M5\White zinc\Carbon steel	FJ21011000022

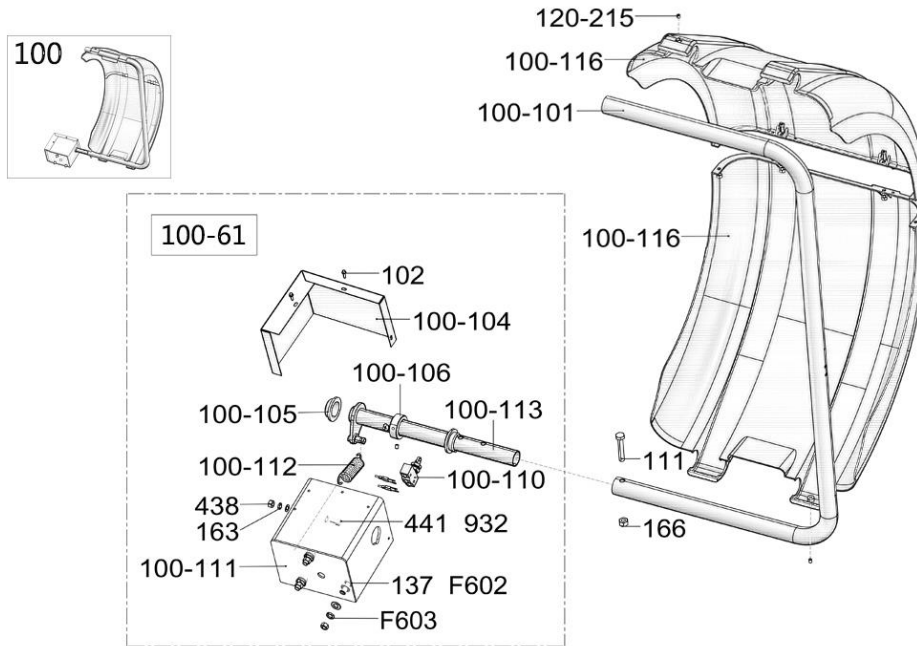
22	Screw	M5*35\White zinc\8.8	FJ22012000073
800-20	Plate	U100	Optional
24	Screw	M5*6\white zinc	FJ19024000007
100-23	Cable circlip	PG13.5\black	DD02001000003



No.	Name	Specification	PLM code
120-213	Gauge sensor	Rv24ynpy20s-b203\20k	DD21001000005
120-205	Measuring Scale	U120	JZ20205100018
120-212	Bobbin winder pulley	U120	JZ12001800073
100-59	Caliper	U100	JZ12001800065
120-209	caliper hook	U120	JZ20203100045
26564	Gauge sensor cable	0.3square*3.0core*L1500.0mm*U820	JZ12400300037
100-208	Graduated Strip	U100	JZ20205100025
800-214	Handle Bar	S728	JZ30303600076
120-206	Heavy	U120	JZ20203100046
131	hex socket head cap screw	M6*16\Turn black\8.8\Carbon steel	FJ22009000093
221-130	Pulley	U120	JZ12001800071
176	screw	M5*10\Turn black	FJ19018000006
120-215	screw	M6*8\Turn black	FJ19006000011
210	screw	M5*8\Turn black	FJ19006000009
120-214	Spring	Medium diameterΦ9.2*Wire diameterΦ0.8*110	JZ11700200029
120-216	Steel rope	Φ1	FJ30008000002

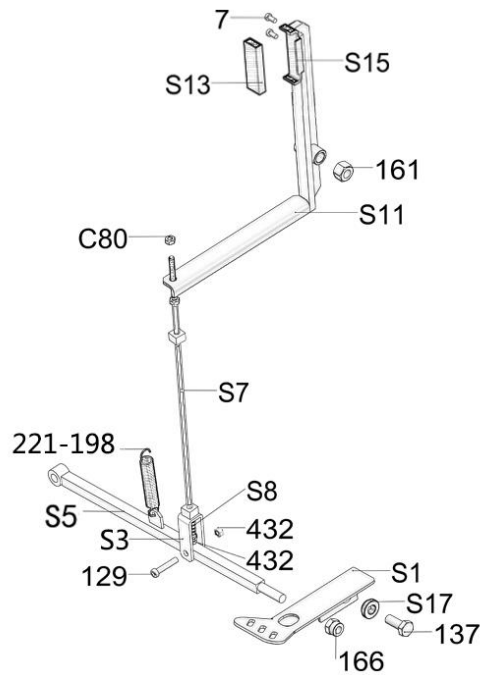


No.	Name	Specification	PLM code
100-308	Threaded shaft Tr36	U100	JZ20203000017
100-306	Position Pick-up Board	U100	JZ12300100126
36-1#	1 CONE Tr36,big	U100	JZ20204400024
36-2#	2 CONE Tr36,medium	U100	JZ20204400025
36-3#	3 CONE Tr36,med-small	U100	JZ20204400026
36-4#	4 CONE Tr36,small	U100	JZ20204400027
100-301	Balancer Belt	380\J5	FJ05001000002
100-310	Big Spring	Φ3*Φ148*L97	JZ11700400025
100-15	capacitance	15uF\450V\Circled with a line	DD20001000004
100-311	Complete shaft	U800	JZ30303600052
100-312	Double-end sensing screw rod	U100	JZ20204600008
5	Flat washer	6*14*1.2\White zinc	FJ15006000095
F602	Flat washer	10*20*2\White zinc\Carbon steel	FJ15006000006
F603	Flat washer	10\Turn black\70#	FJ15004000002
302	Flat washer	10*30*3\White zinc\Carbon steel	FJ15006000010
159	Flat washer	10*40*3\White zinc	FJ15006000012
320	Support of Position Pick-up Board	U100	JZ20204600016
601-MC	Motor	220-240V\50HZ\1PH\0.2KW	DD01001000072
C80	Nut	M6\White zinc\Carbon steel	FJ21011000023
314	Nut	M10\Turn black	FJ21010000003
303	Outer hex bolt	M10*25\Turn black\8.8	FJ22014000001
238-913	Plastic lid	U100	JZ12000200138
100-309	Plastic Lid Tr36	U100	JZ12000200127
238-912	Pressure ring	U570	JZ12001800077
238-911	Quick release nut Tr36	U800	JZ30303600003
238-914	Rubber Buffer	U100	JZ20204500036
307	screw	M3*6\Nickel plating	FJ19024000003
100-315	Sensor Assembly	Balancing machine	DD18010000003
100-317	Single-end sensing screw rod	U100	JZ20204600006
313	Washer	23*3\Turn black\65Mn	FJ15001000001



No.	Name	Specification	PLM code
100-116	Protection Hood Assembly	U100	JZ12000200126
100-104	Cover for protection hood box	U100*Wrinkle RAL9005	JZ20202800024
F603	Flat washer	10\Turn black\70#	FJ15004000002
163	Flat washer	8\Turn black\70#	FJ15004000021
F602	Flat washer	10*20*2\White zinc\Carbon steel	FJ15006000006
932	Flat washer	8*17*1.5\White zinc	FJ15006000107
441	hex socket head cap screw	M8*20\Turn black\8.8\Carbon steel	FJ22009000123
100	LW-Hood	U100/1 Contains the axle box	JZ30303600101
100-110	Micro switch	CM-1308N	DD12007000001
166	Nut	M10\White zinc\Carbon steel\9	FJ21003000001
438	Nut	M8\Turn black	FJ21011000025
111	Outer hex bolt	M10*45\Turn black\8.8	FJ22012000017
137	Outer hex bolt	M10*25\Turn black\8.8	FJ22012000010
102	outer hex self-tapping and self-auger screw	ST4.8*16\Turn black\8.8	FJ19005000001
100-61	Protect axle box assembly	U500	JZ30303600108
100-111	Protection Hood Box	U100*Wrinkles RAL9005	JZ20202800022
100-101	Protection Hood Rotating Shaft	U100*Plain light RAL9005	JZ20203100133
100-113	Protection hood shaft	U800*Wrinkles RAL9005	JZ20202800021
100-106	Protection hood shaft sleeve	U800	JZ12000200150
100-112	Protection hood spring	Medium diameterΦ25*Wire diameterΦ3.5*86	JZ11700200023
120-215	screw	M6*8\Turn black	FJ19006000011
100-105	Sheath	U800	JZ12001800078

S Version Exploded drawings and spare parts list



No.	Name	Specification	PLM code
S11	Brake lever	U100	JZ20202900005
S15	brake lever	U100	JZ20202900013
S13	brake pad	U100	JZ20202900067
S1	brake pedal	U100	JZ20202900010
S7	Connecting rod	U100	JZ20202900007
S3	draw hook	U100	JZ20202900009
S5	foot lever	U102	JZ20202900017
221-198	Hex locking board spring	Medium diameter Φ 9*Wire diameter Φ 1.5*54	JZ11700200017
129	hex socket head cap screw	M6*35\Turn black	FJ22009000103
166	Nut	M10\White zinc\Carbon steel\9	FJ21003000001
161	Nut	M12\White zinc\Carbon steel\9	FJ21003000002
C80	Nut	M6\White zinc\Carbon steel	FJ21011000023
432	Nut	M6\White zinc\Carbon steel\9	FJ21003000013
137	Outer hex bolt	M10*25\Turn black\8.8	FJ22012000010
S17	rotating sleeve	U100	JZ20202900012
7	screw	M5*10\Turn black	FJ19018000006
S8	Spring	L28*Medium diameter Φ 10*Wire diameter Φ 2	JZ11700300058

Accessories list

CODE	ITEM	QTY	PHOTO	
JZ20204400024	1# CONE	1		Φ36
JZ20204400025	2# CONE	1		Φ36
JZ20204400026	3# CONE	1		Φ36
JZ20204400027	4# CONE	1		Φ36
JZ30303600003	COMPLETE QUICK RELEASE NUT	1		Φ36
JZ20203000017	THREADED SHAFT	1		Tr36
JZ20203100029	WRENCH	1		
GF29009000001	HEX WRENCH	1		
GF29009000003	HEX WRENCH	1		
JZ20204800001	STANDARD WEIGHTS 100G	1		
JZ12001800065	CALIPER	1		
JZ11801300051	PLIER	1		
JZ12000200138	PLASTIC LID	1		
JZ20204500036	RUBBER BUFFER	1		

Attach figure 1

System circuit diagram

